

3 the assumed-movement pattern includes video data showing virtual
4 poles arranged on the outer edge of the vehicle movement area.

1 9. (Amended) The driving-operation assist according to [any one
2 of] claim[s] 6 [to 8], characterized in that

3 the synthetic-image generating means superimposes current-position
4 data serving as video data showing an area in which the vehicle is present, on the
5 circumferential-state image to generate the synthetic image.

1 11. (Amended) The driving-operation assist according to [any one
2 of] claim[s] 6 [to 10], characterized in that when actual driving operations
3 corresponding to the above predetermined series of driving operations are started,

4 the synthetic-image generating means thereafter fixes the positional
5 relation between the assumed-movement pattern and the circumferential-state
6 image at the point of time when the actual driving operations are started and
7 generates the synthetic image.

1 14. (Amended) The driving-operation assist according to [any one
2 of] claim[s] 6 [to 13], characterized in that

3 final-position inputting means for inputting a final position which is
4 a position of the vehicle at end of the movement and start-position determining
5 means for obtaining a start position which is a position at start of the movement
6 corresponding to the input final position in accordance with the assumed-
7 movement pattern are included, and

8 the synthetic-image generating means superimposes the input final
9 position and the start position corresponding to the input final position on the
10 circumferential-state image to generate the synthetic image.

1 16. (Amended) The driving-operation assist according to any one of
2 claims 1 to [15]4, characterized in that

3 assumed-movement-pattern storing means is included which holds
4 data relating to the above predetermined series of driving operations and holds

5 assumed-movement data including at least the assumed-movement pattern.

1 18. (Amended) The driving-operation assist according to claim 16
2 [or 17], characterized in that pattern correcting means is included which is able to
3 update and correct the content of the assumed-movement pattern held in the
4 assumed-movement-pattern storing means.

1 21. (Amended) The driving-operation assist according to [any one
2 of] claim[s] 16 [to 20], characterized in that the assumed-movement data includes
3 time-series data showing a relationship between a movement distance and a
4 steering angle of the steering wheel of the vehicle.

1 23. (Amended) The driving-operation assist according to [any one
2 of] claim[s] 11 [to 13 or claim 22], characterized in that operation-start detecting
3 means is included which automatically detects that actual driving operations
4 corresponding to the above predetermined series of driving operations are started
5 through an input from a driver or a predetermined driving operation.

1 24. (Amended) The driving-operation assist according to [any one
2 of] claim[s] 5 [to 23], characterized in that

3 when the viewpoint converting means changes the predetermined
4 viewpoint, the viewpoint converting means fixes the predetermined viewpoint to
5 the vehicle before the actual driving operations corresponding to the
6 predetermined series of driving operations are started and changes the
7 predetermined viewpoint to a point fixed to the three-dimensional space after the
8 actual driving operations corresponding to the predetermined series of driving
9 operations are started.

1 26. (Amended) The driving-operation assist according to any one of
2 claims 1 to [5]4, characterized in that the assumed-movement pattern includes
3 video data showing a circumscribed area on a space through which the vehicle
4 passes when the predetermined series of driving operations are performed.

1 29. (Amended) The driving-operation assist according to any one of

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2 claims 1 to [5]4, characterized in that the assumed-movement patterns respectively
3 include a change from backward movement to forward movement or from forward
4 movement to backward movement in the predetermined series of driving
5 operations

30. (Amended) The driving-operation assist according to any one of
claims 1 to [5]4, characterized in that obstacle inputting means is included which
is able to input a position of an obstacle area in an image to displaying means for
displaying the synthetic image from a driver.

1 33. (Amended) A recording medium characterized by storing a
2 program of making a computer execute all of some of functions of each means of
3 any one of claims 1 to [32]4.

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1 34. (Newly Added) The driving-operation assist according to claim
2 12, characterized in that operation-start detecting means is included which
3 automatically detects that actual driving operations corresponding to the above
4 predetermined series of driving operations are started through an input from a
5 driver or a predetermined driving operation.

1 35. (Newly Added) The driving-operation assist according to

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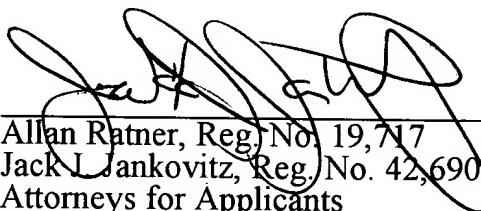
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2 claim 13, characterized in that operation-start detecting means is included
3 which automatically detects that actual driving operations corresponding to the
4 above predetermined series of driving operations are started through an input
5 from a driver or a predetermined driving operation.

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1 36. (Newly Added) The driving-operation assist according to
2 claim 22, characterized in that operation-start detecting means is included
3 which automatically detects that actual driving operations corresponding to the
4 above predetermined series of driving operations are started through an input
5 from a driver or a predetermined driving operation.

Respectfully Submitted,

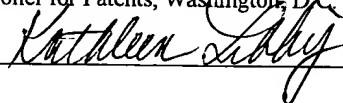

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